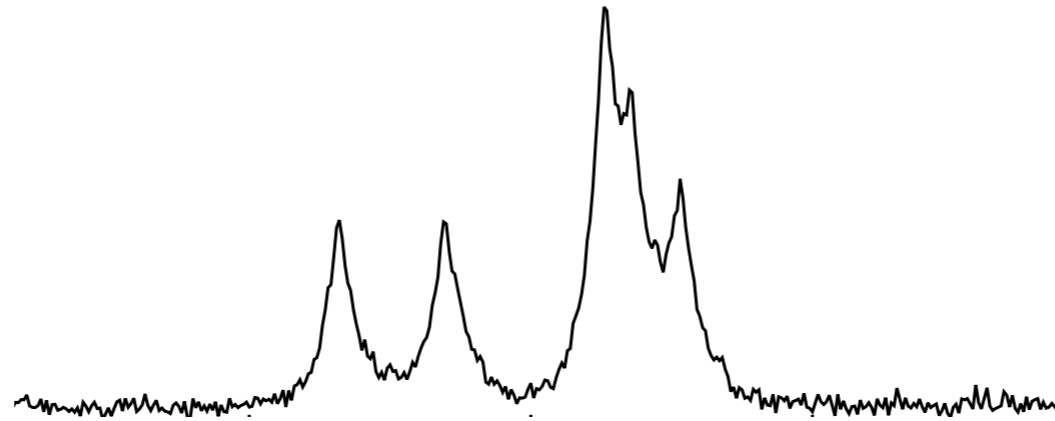


# STATISTICAL ANALYSIS OF MULTIWAVELENGTH LIGHT CURVES



FERMI AND JANSKY  
OUR EVOLVING UNDERSTANDING OF AGN  
ST. MICHAELS  
10 NOV 2011

STEFAN LARSSON  
STOCKHOLM UNIVERSITY  
“WITH ~~A LITTLE~~ HELP OF MY FRIENDS”  
IN THE FERMI COLLABORATION

## **AIM?**

Characterize variability and MW correlations  
and/or  
Test theoretical models

## **ALSO**

Discover new phenomena

## **WITH**

Light curves and statistical tools

## **COMPLICATIONS**

S/N, sampling, time resolution, obs length,  
non-stationarity, tac, world economy ...

## DATA?

Fermi: Regular sampling, high duty cycle. Low to moderate S/N  
(Events or binned?)

Radio: Semi regular at best, but higher S/N

## TOOLS?

Variability:

Variance

Flare profile fitting

Flux duty cycles

Power Density Spectra

Auto Correlation Function

Structure Function

Wavelets

MW Correlation:

Direct light curve comparison

Flux - Flux plots, tracks (possibly with time lags)

Cross Correlation Function

Cross Spectrum

**THIS TALK WILL FOCUS ON PRACTICAL ASPECTS OF  
CROSS CORRELATION ANALYSIS**

**FOR A WIDER OVERVIEW SEE:**

**“METHODS FOR CROSS-ANALYZING RADIO AND GAMMA-RAY TIME SERIES DATA”**

**JEFF SCARGLE**

**WHEN FERMI MET JANSKY IN 2010**

Recipes to calculate the Cross Correlation Function for unevenly sampled light curves:

*DCCF, Discrete CCF (Edelson & Krolik, 1988)*

*ICCF, Interpolated CCF (e.g. Gaskell & Peterson, 1987)*

*ZCCF, Z-transform CCF (Alexander, 1997)*

*Inverse FT of PDS (Scargle, 1989)*

In most cases we want:

1. Strength and significance of correlation
2. Lag between the two light curves, with uncertainty

## DISCRETE CCF (EDELSON & KROLIK, 1988)

The classical CCF:

$$CF(\tau) = \frac{E\{[a(t) - \bar{a}][b(t + \tau) - \bar{b}]\}}{\sigma_a \sigma_b}, \quad (2)$$

For each pair of points in LC 1 and 2 compute their contribution to the CCF at the lag corresponding to their time separation

Pair by pair

Unbinned DCF:

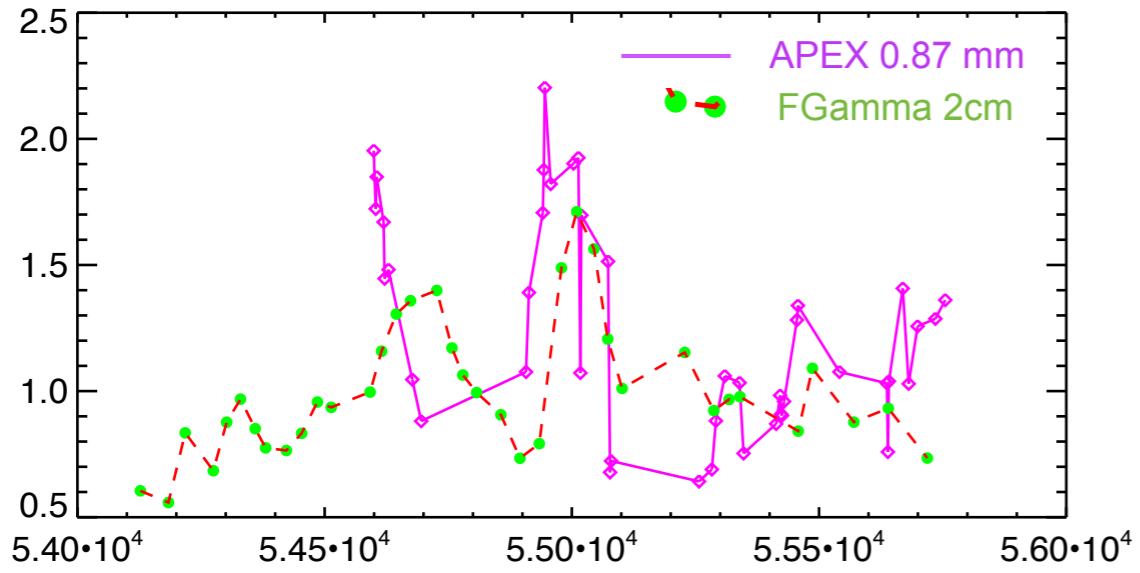
$$UDCF_{ij} = \frac{(a_i - \bar{a})(b_j - \bar{b})}{\sqrt{(\sigma_a^2 - e_a^2)(\sigma_b^2 - e_b^2)}}, \quad (3)$$

$e$  = rms measurement errors

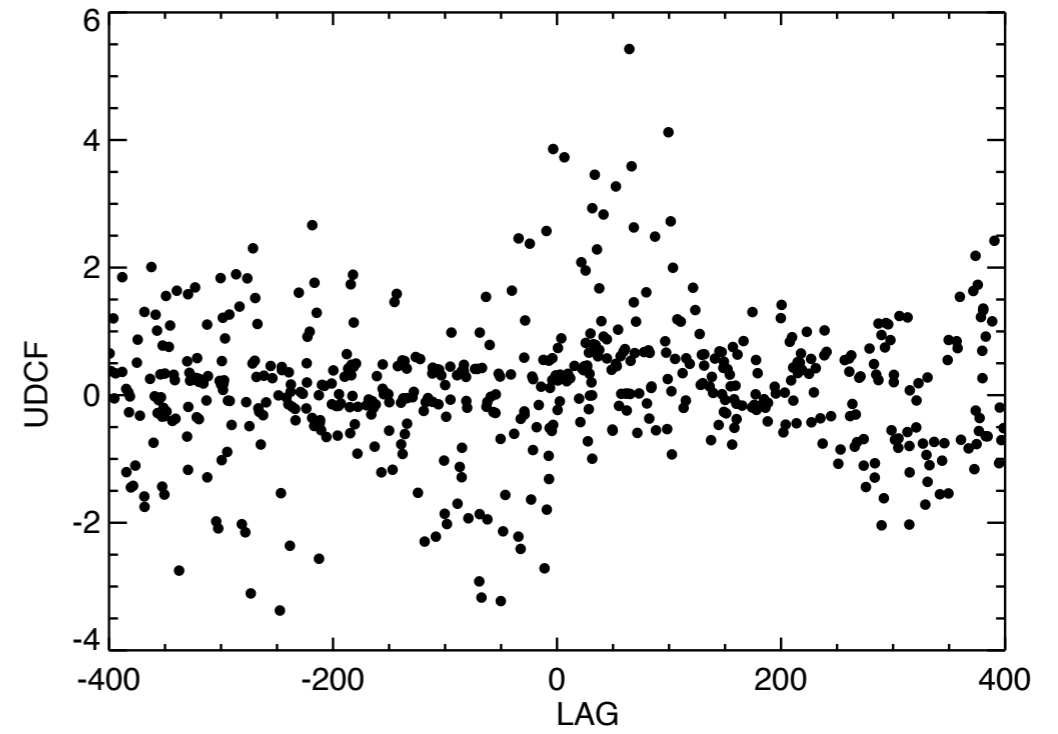
Bin (average) the UDCF => DCCF

# DCCF EXAMPLE

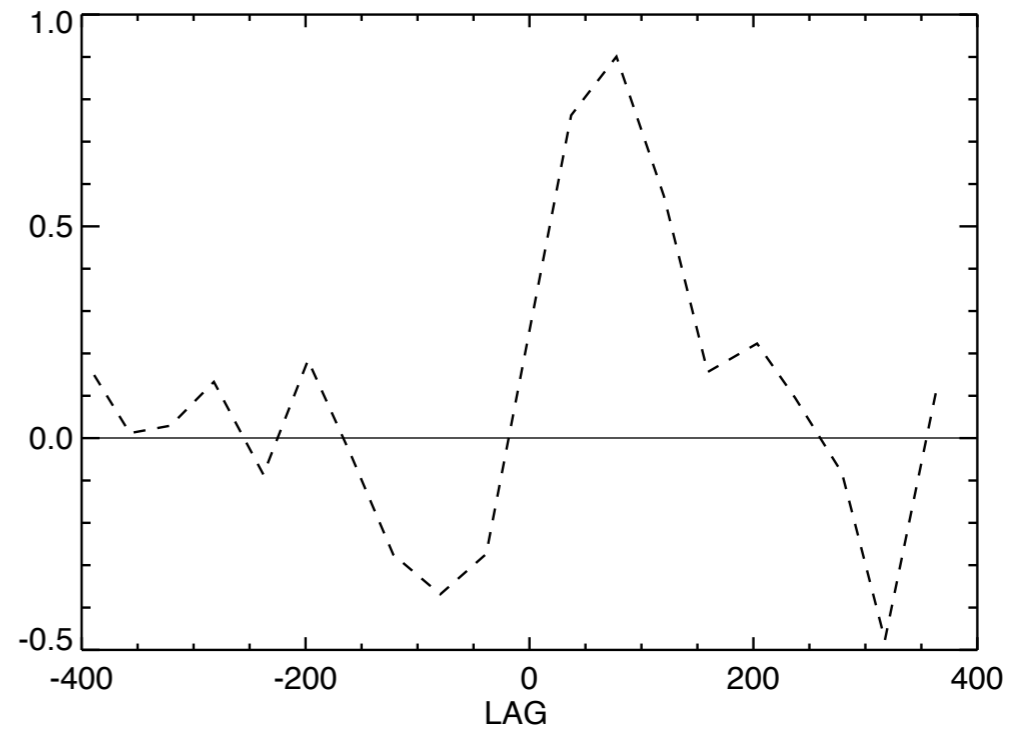
PKS 1510-089



Unbinned DCF:



Bin (average) the UDCF => DCCF



# THE CCF IS AFFECTED BY

1) Measurement noise

2) Time sampling

3) Stochastic variability

- Different realizations of the same stochastic process will have different PDS/ACF/CCF
- Chance correlations (E.g. 2 independent short LCs with one flare each will show a strong correlation at a lag corresponding to the time shift between the flares)



## EXAMPLE OF MODEL DEPENDENT MONTE CARLO METHOD FOR CCFs

1. Simulate two light curves with some correlation and lag.
2. Sample the two LCs
3. Add errors
4. Compute CCF
5. Determine Lag
6. Repeat N times
7. Compute Lag distribution

Compare to the previous talk where Walter Max-Moerbeck used phase randomization of the Fourier transformed data to estimate correlation significances.

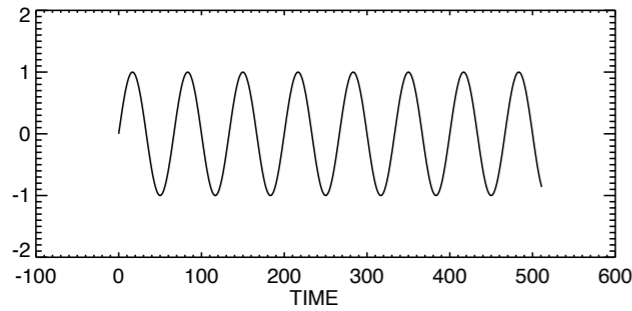
**A MODEL INDEPENDENT MONTE CARLO METHOD (PETERSON ET AL, 1998)  
TO ADDRESS ERROR POINTS 1 AND 2 (MEASUREMENT NOISE AND  
SAMPLING) BUT NOT 3 (STOCHASTIC VARIATIONS).**

- 1) Add 1 sigma errors to the data
- 2) Make a bootstrap-like point selection.
- 3) Compute CCF and determine Lag of the peak
- 4) Repeat N times and compute rms(lag)

Note 2: A recipe to compute Lag error not DCCF point errors!  
(You can still do that if you keep in mind that the different lag points are correlated).

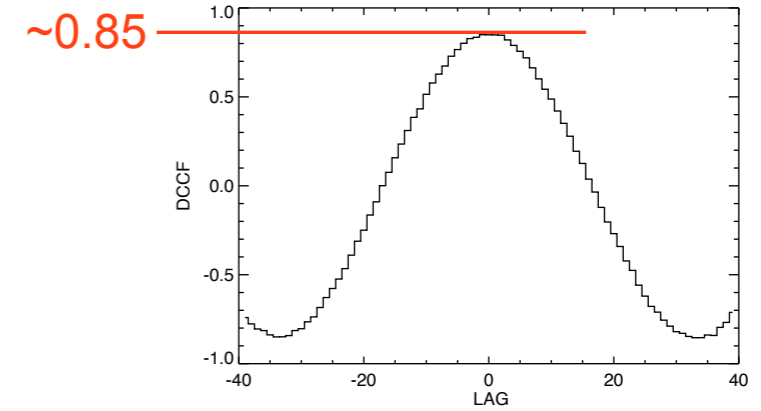
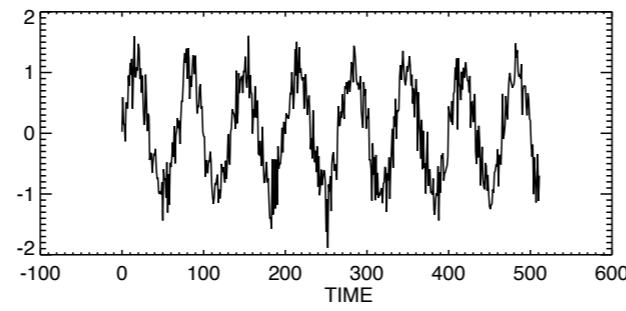
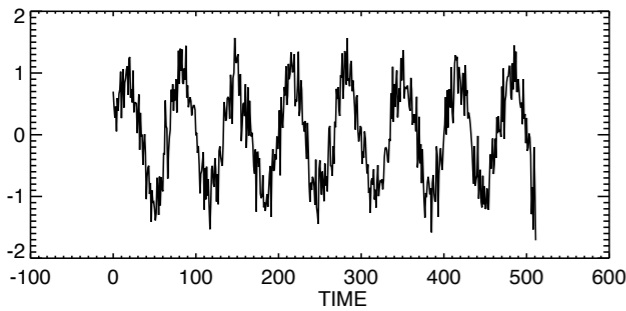
# 1) MEASUREMENT NOISE

Two “observations” of the same light curve with added noise (independent gaussian noise).

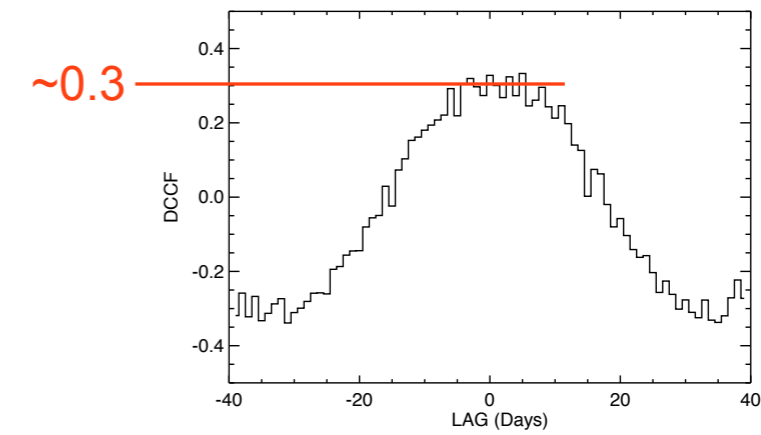
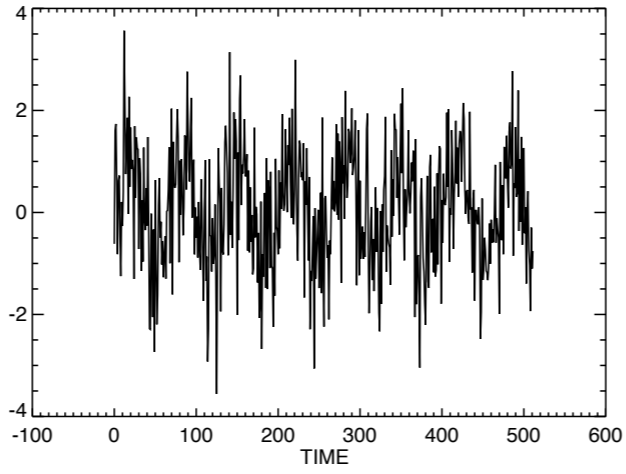
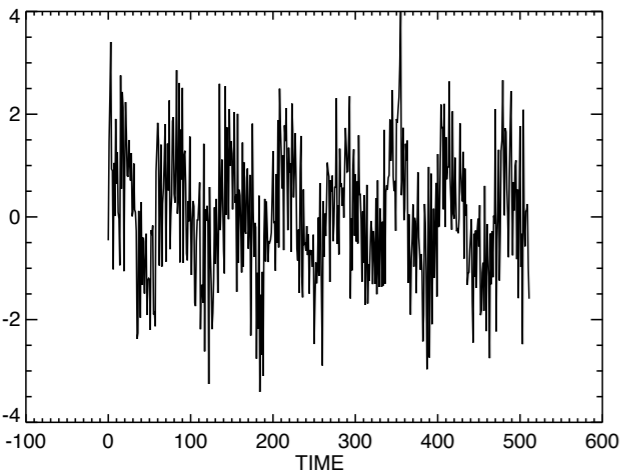


512 points Sine ampl = 1

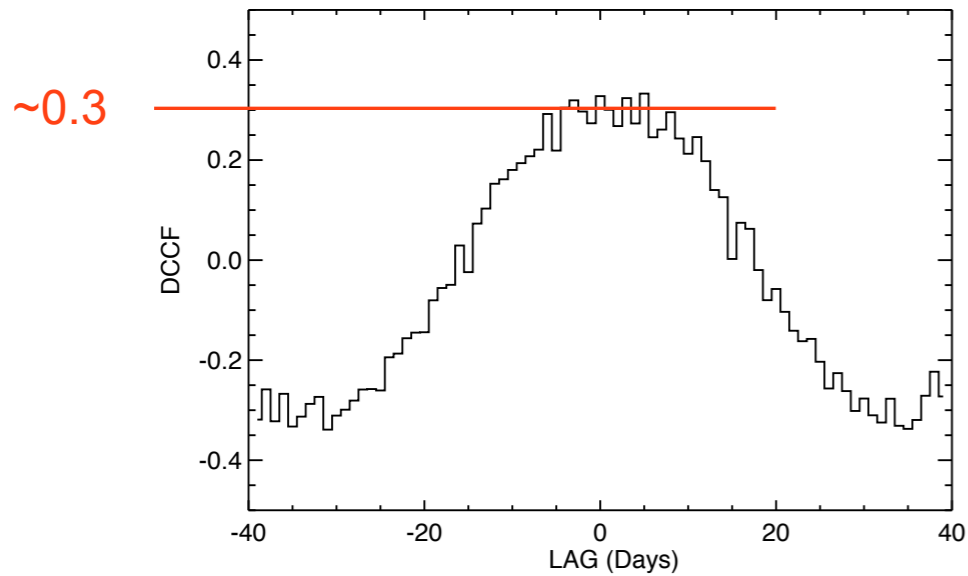
rms noise = 0.3



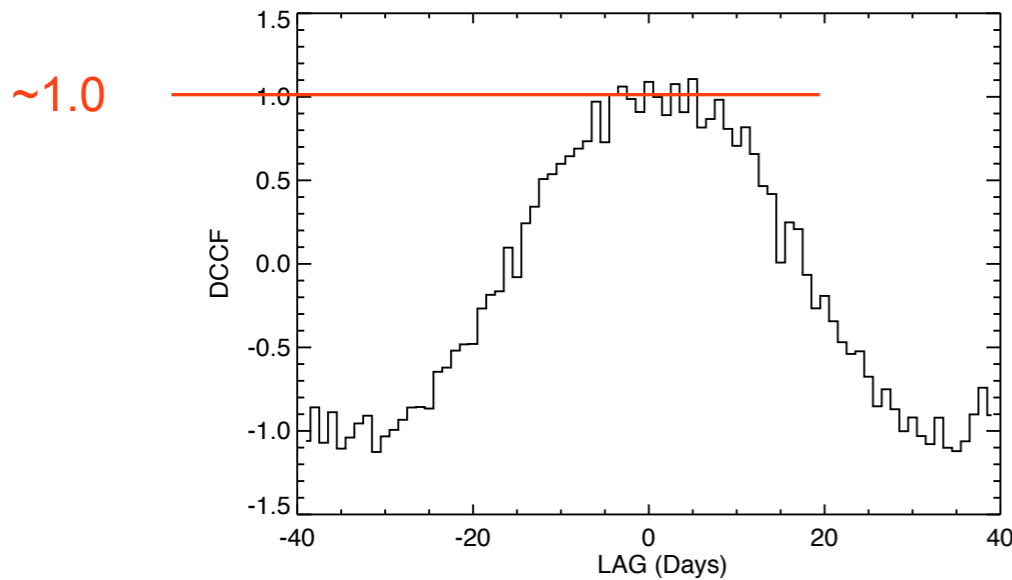
rms noise = 1.0



# 1) MEASUREMENT NOISE



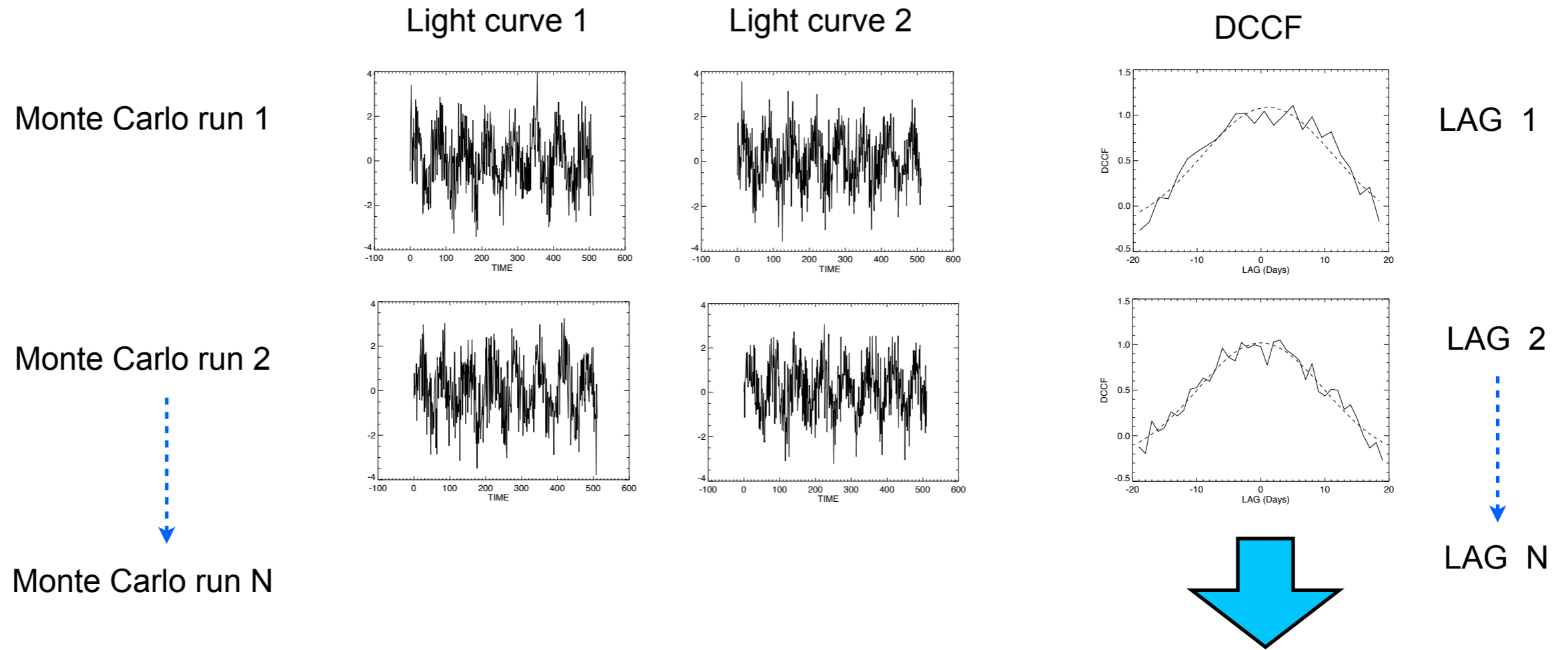
Correcting for the de-correlation due to white noise



$$\text{UDCF}_{ij} = \frac{(a_i - \bar{a})(b_j - \bar{b})}{\sqrt{(\sigma_a^2 - e_a^2)(\sigma_b^2 - e_b^2)}}, \quad (3)$$

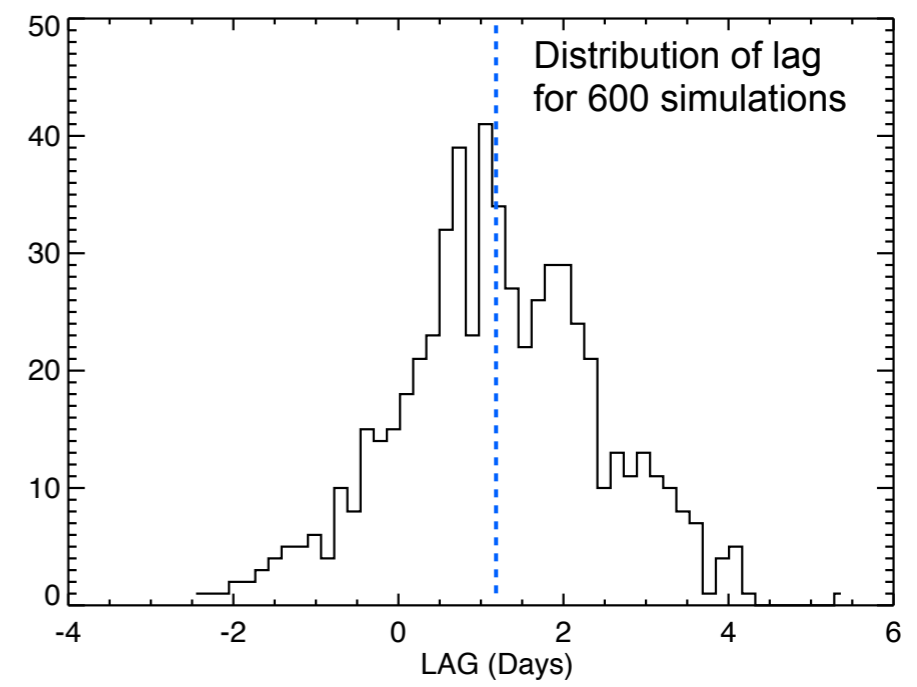
$e$  = rms measurement errors

# PETERSON'S RECIPE 1: INJECTING WHITE NOISE



Distribution of Monte Carlo Lags gives uncertainty

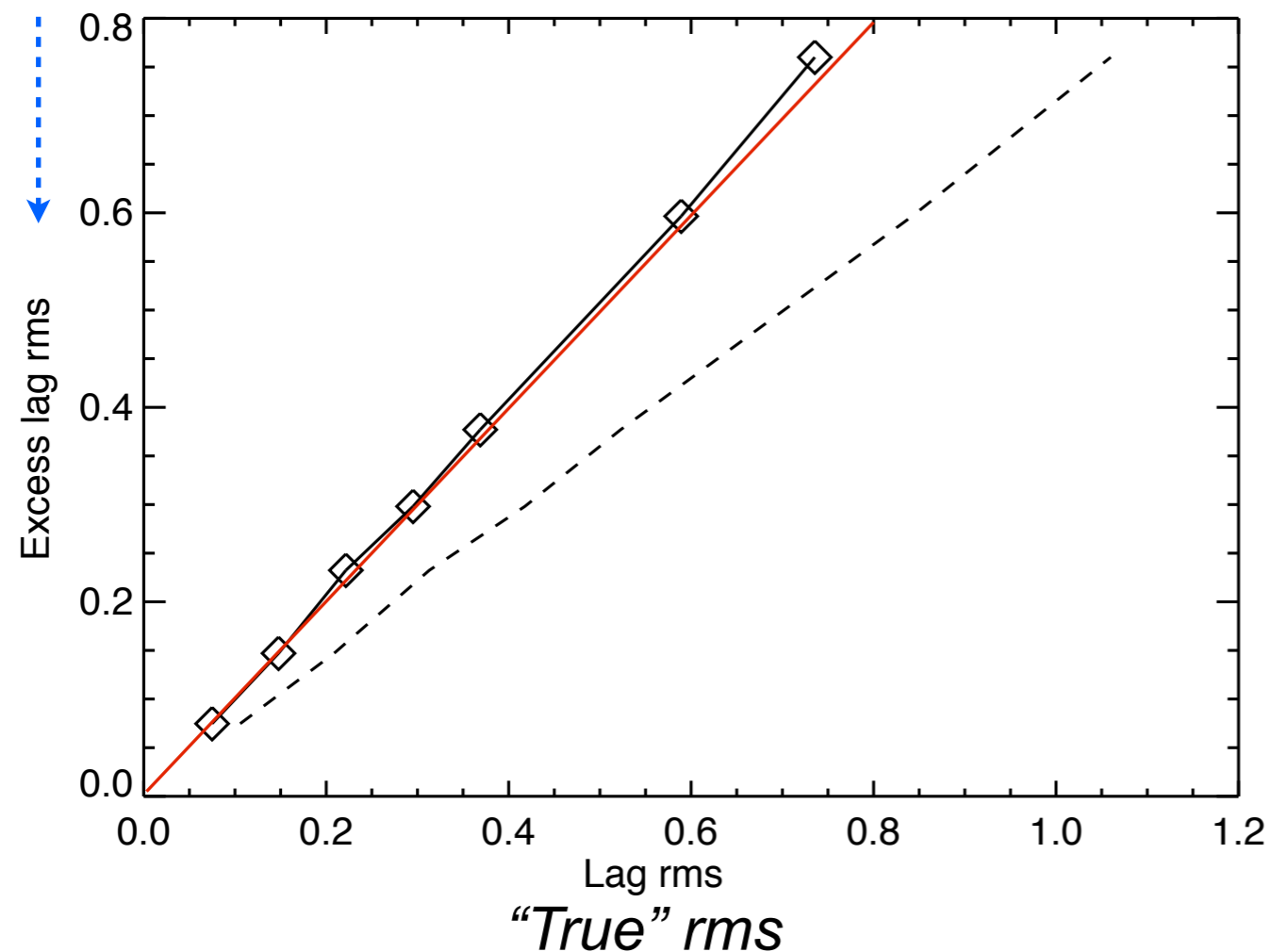
“Cross Correlation Peak Distribution” (CCPD), Maoz & Netzer (1989)



# PETERSON'S RECIPE 1: INJECTING WHITE NOISE

Test of the error estimation  
with known input (Simulated  
data with different S/N)

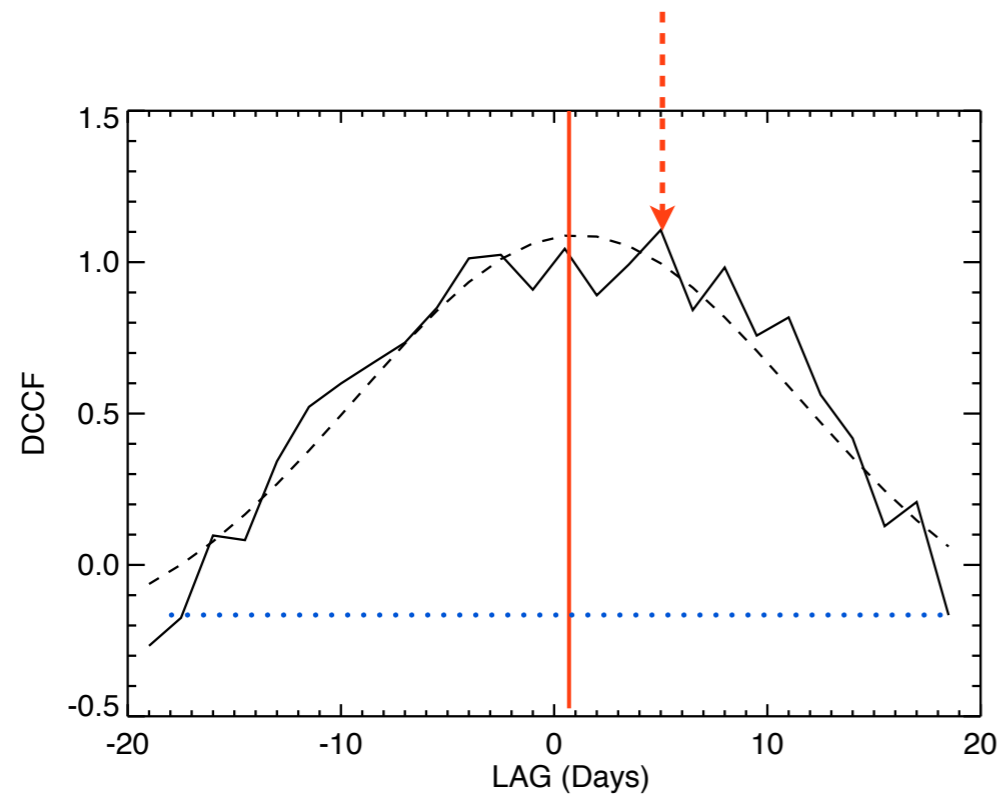
Excess lag rms is relative  
to the analyzed LC



- White noise added to one light curve*
- White noise added to both light curves*
- Assumption of error linearity (from light curve to lag estimate)*

# WHAT IS THE LAG AT THE PEAK?

- The highest value of the DCCF?
- Centroid?
- Max of a fitted function?



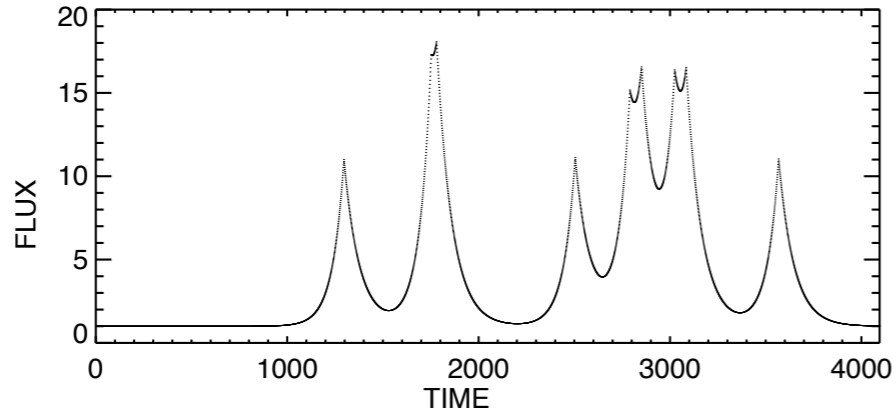
Gaussian fit to estimate correlation peak  
[I use gaussian just for convenience]

Wide enough to get a reasonable fit but  
not so wide that it is determined by the  
base. (Wade & Horne, 1998)

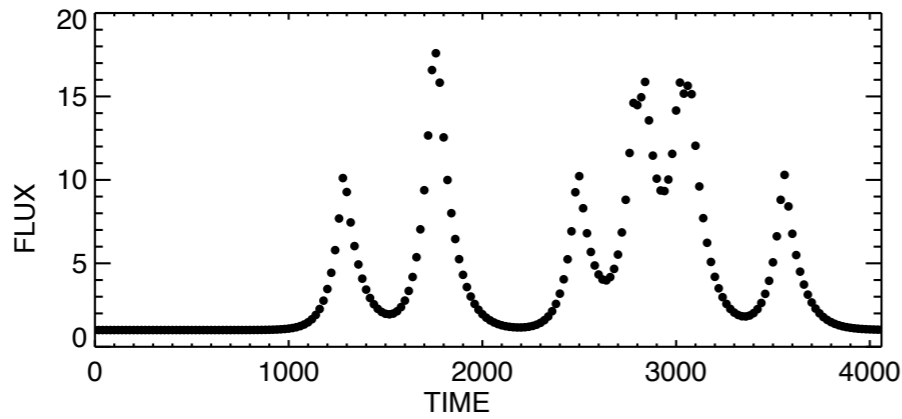
# PETERSON'S RECIPE 2: UNEVEN SAMPLING

Let's make a simulation....

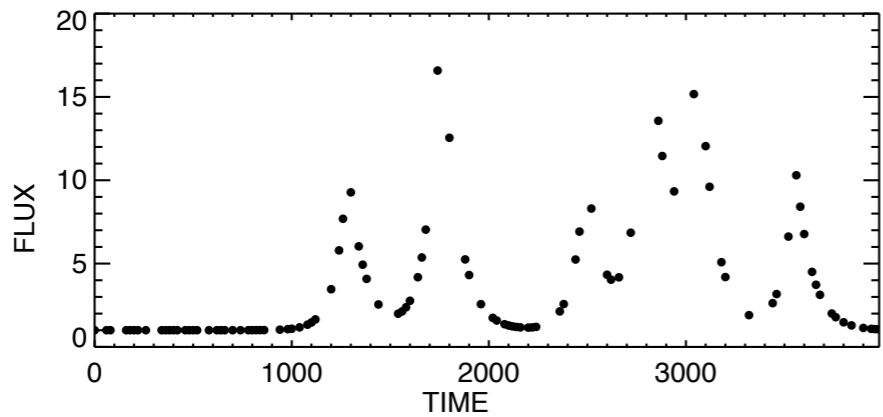
*True  
light curve  
(no noise)*



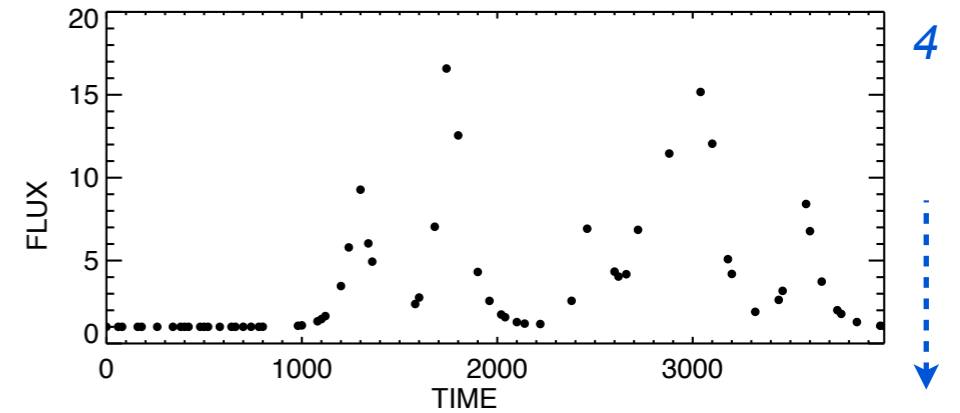
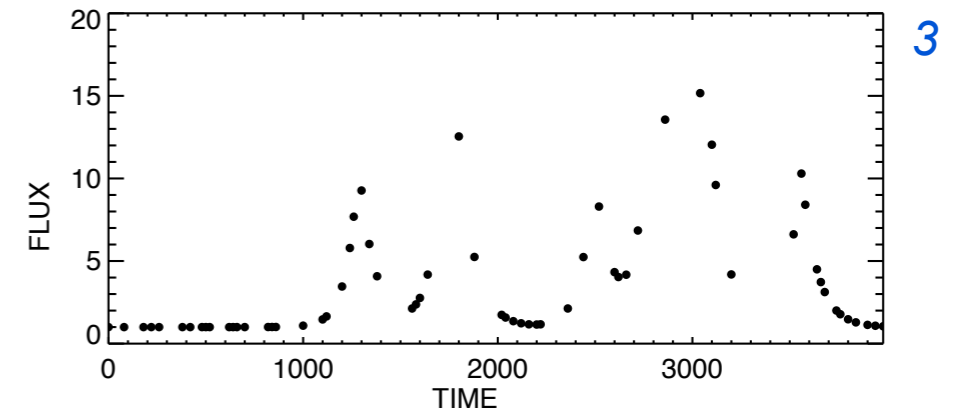
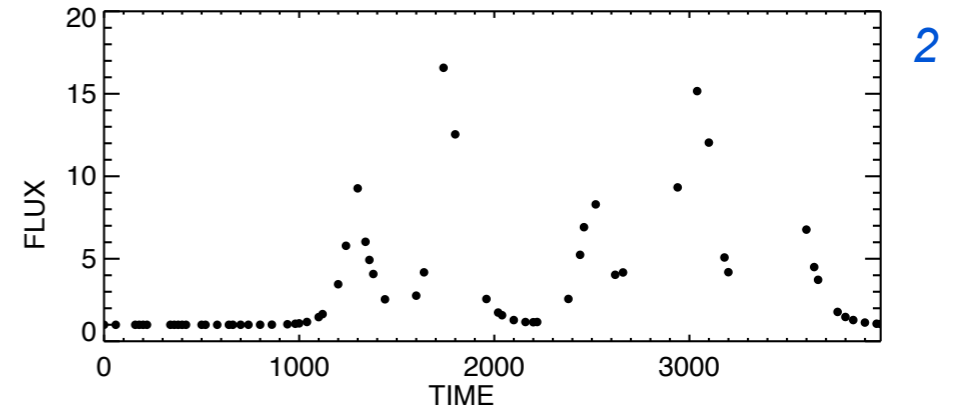
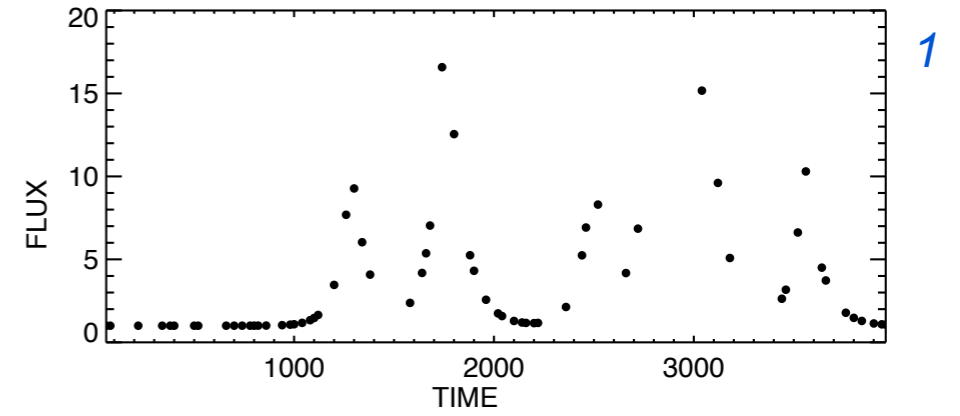
*Evenly  
sampled  
204 points*



*100 random  
observations  
of the LC*



*"Bootstrap" resampling*



*N*



Close to detection limit you may have to run separate MCs and add variances,

Variance (errors LC 1) + Variance (errors LC 2) + Variance Bootstrap

## DCCF SIGNIFICANCES BY MIXED SOURCE CORRELATION

Fermi and Radio monitoring programs are now providing light curves for a large number of sources.

Assuming that all sources have similar variability properties

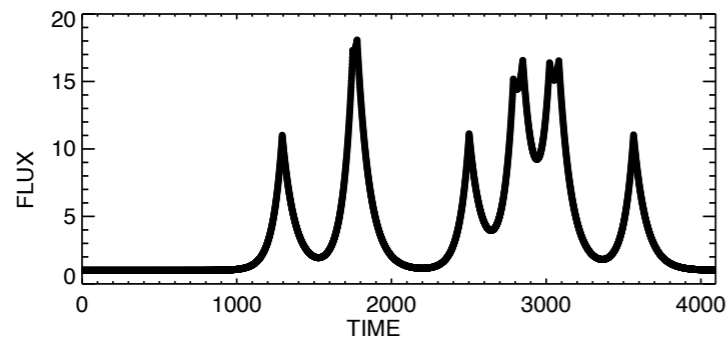
We can estimate the probability of stochastic chance correlations by correlating each radio light curve with the gamma-ray light curves of all the other sources. [Gamma is evenly sampled but radio is not!]

Advantage: Requires no characterization of the variability

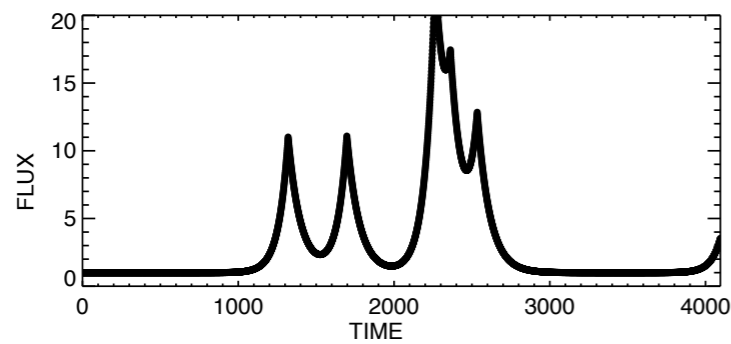
Disadvantage: Limited number of test light curves

# DCCF SIGNIFICANCES BY MIXED SOURCE CORRELATION

Gamma  
JXXXX

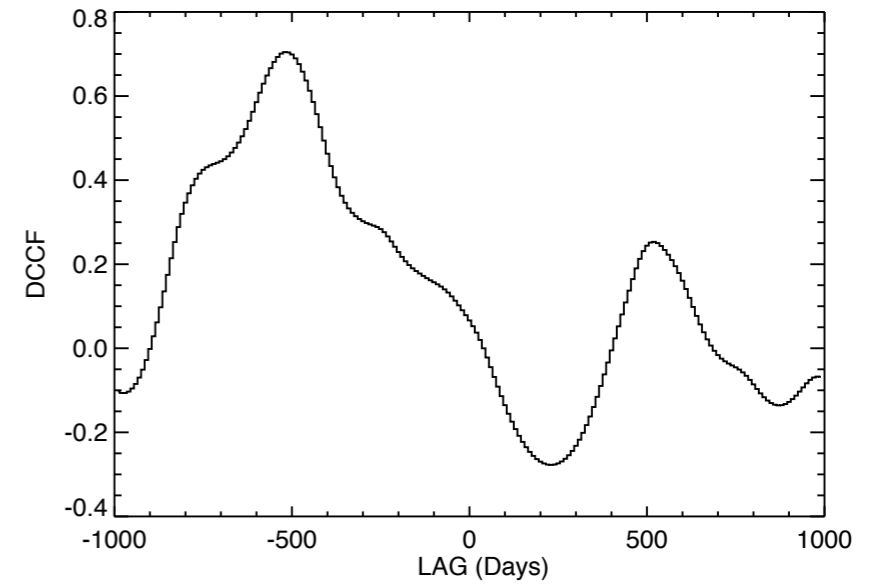


Radio  
JYYYY

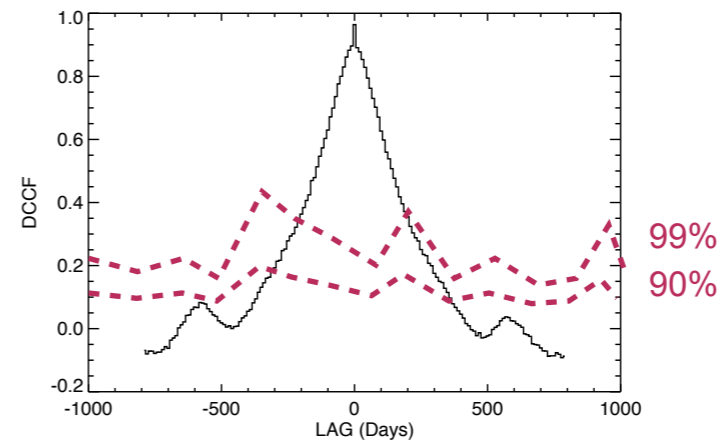
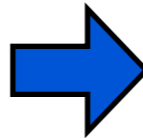
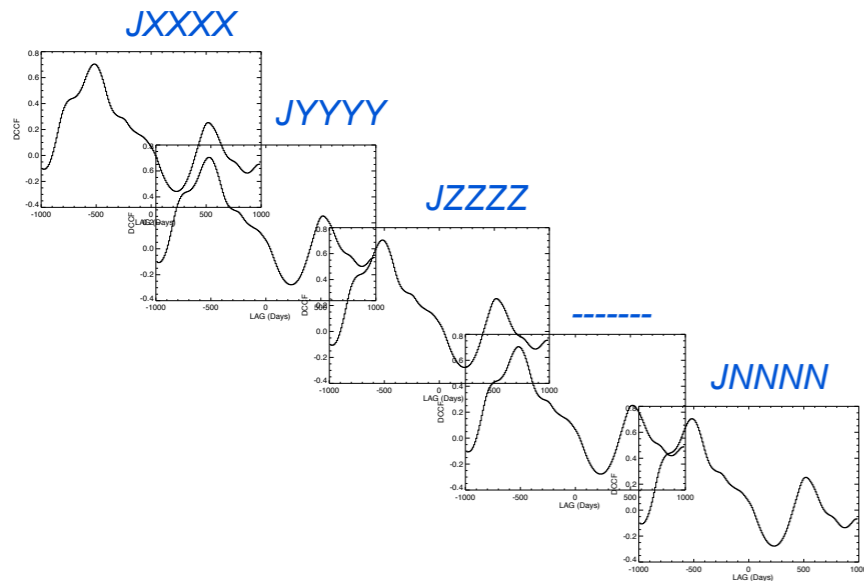


DCCF

Loop over all "JYYYY"  
Compare DCCF  
distribution with  
source DCCF



# AVERAGE THE DCCFs FOR A SAMPLE OF SOURCES



AND do the same for the corresponding samples of mixed DCCFs

➡ A comparison sample of N-1 DCCFs

Applied to 3 years of Gamma - Radio data (Fermi & FGamma)  
[talk by Lars Fuhrmann]

# ARE CORRELATION PROPERTIES PERSISTENT?

We can analyze segments of the data to

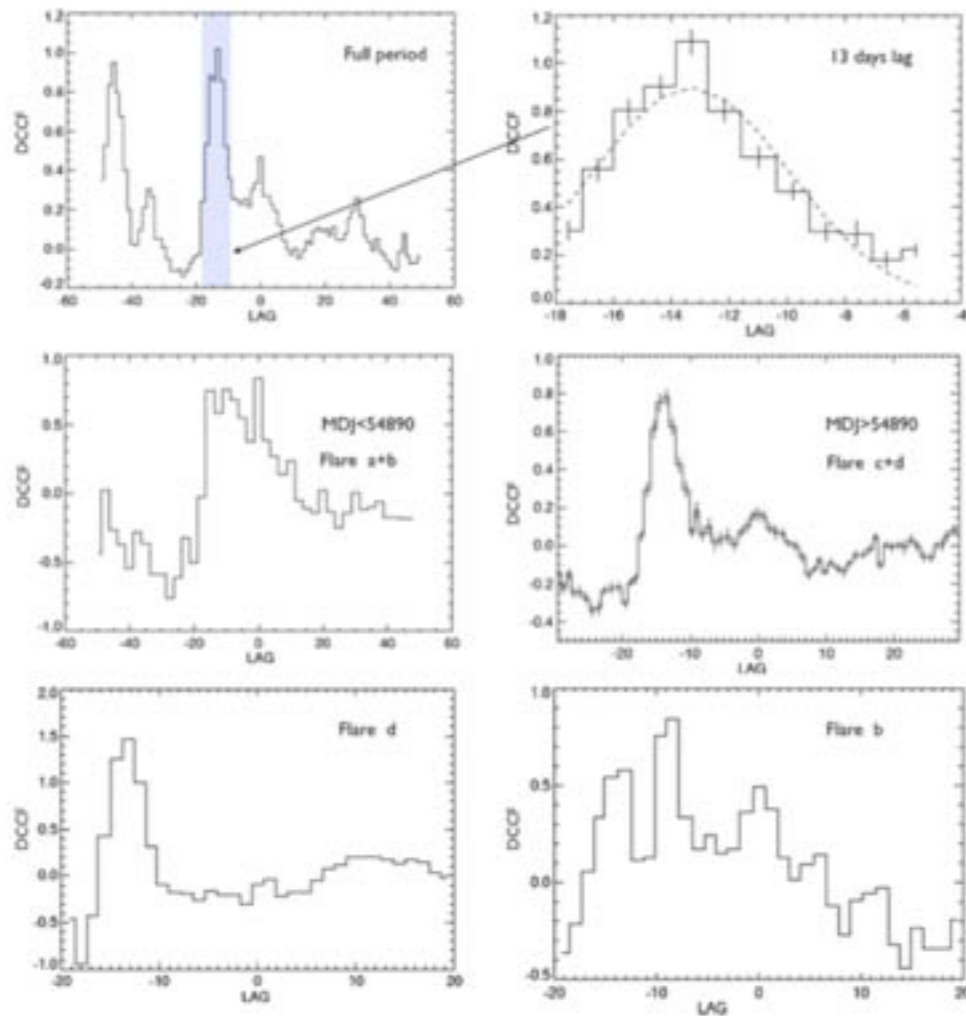
- 1) Evaluate the significance of the correlation
- 2) Look for variations in correlation properties

Various observations have revealed variations in MW lags with time.  
Such variations can reflect either:

- Real physical changes in the source
- Stochastic variations [Check by ACF/PDS]

Cross correlations show ~13 day lag (R lagging gamma) both for the total light curve and for the individual flares + correlation on time scales of < 2 days

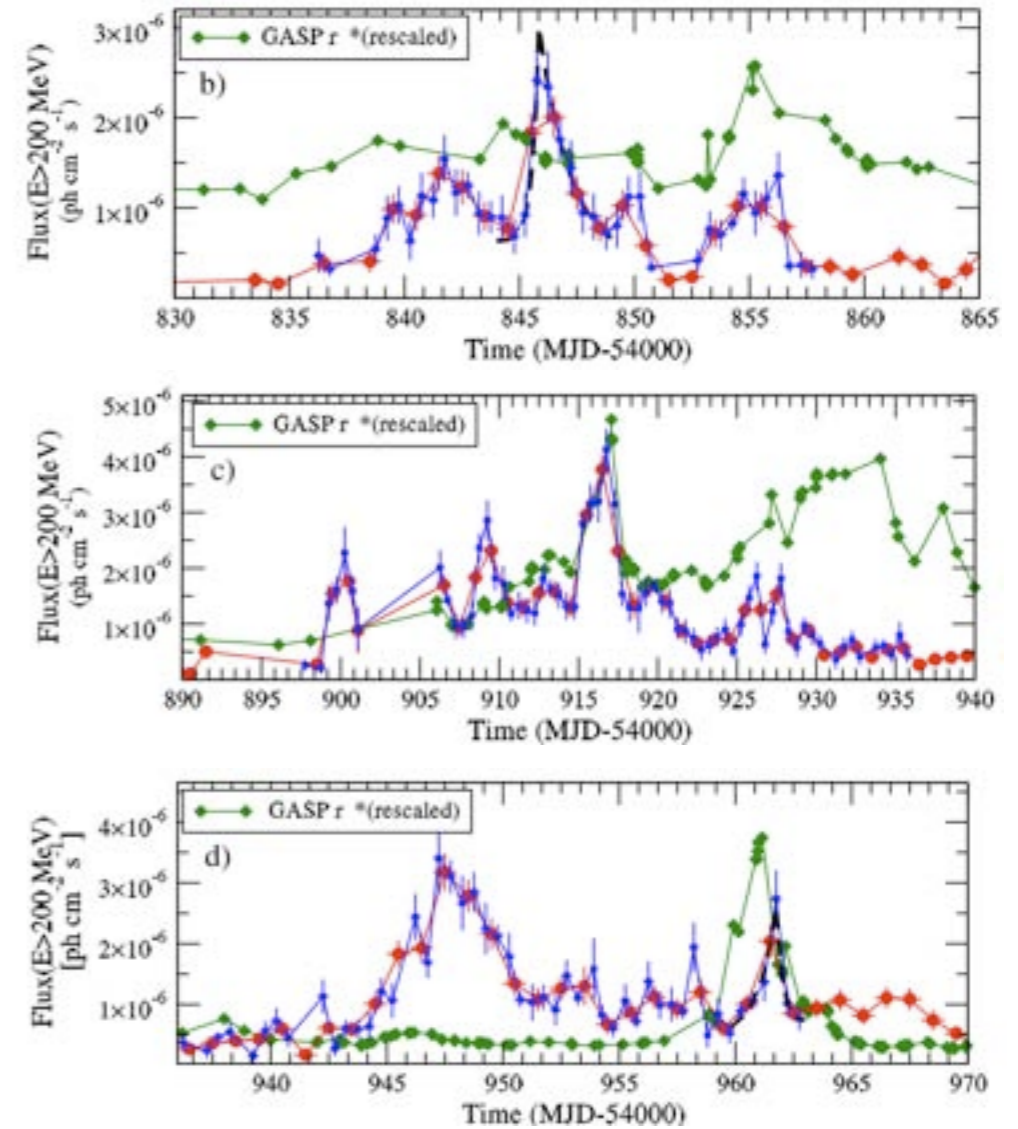
While R and gamma show correlations on time scales < 2 days the ratio of R flux to gamma flux increases towards the end of the flare. This is the cause of the observed 13 day lag.



DCCF for all flares

DCCF for a+b and c+d

DCCF for d and b



## DETRENDING

(e.g. polynom subtraction)

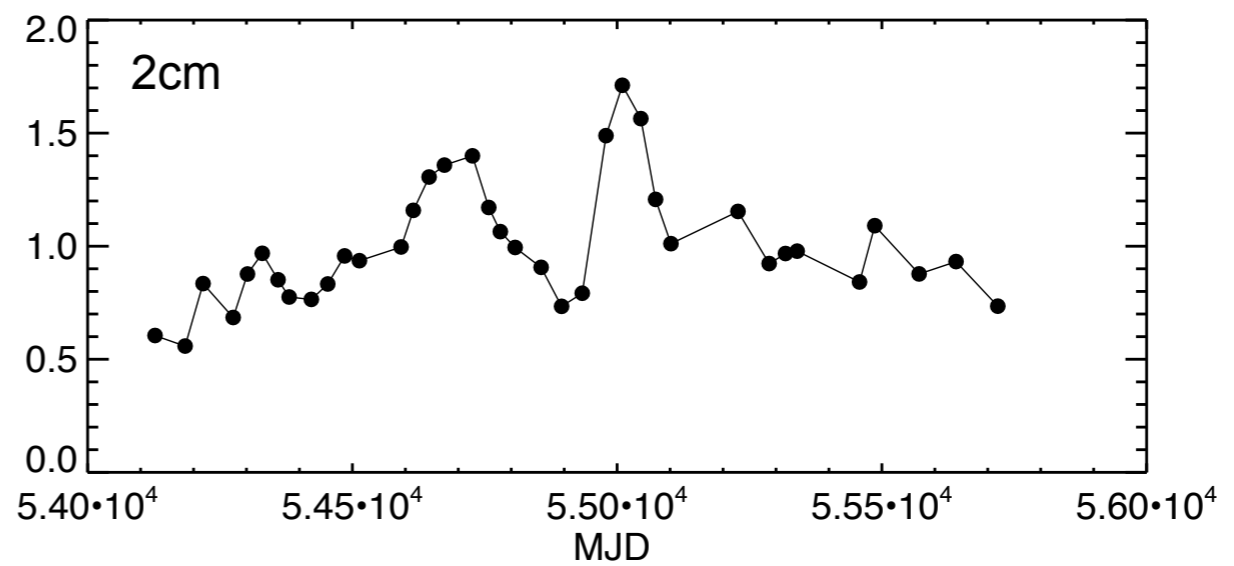
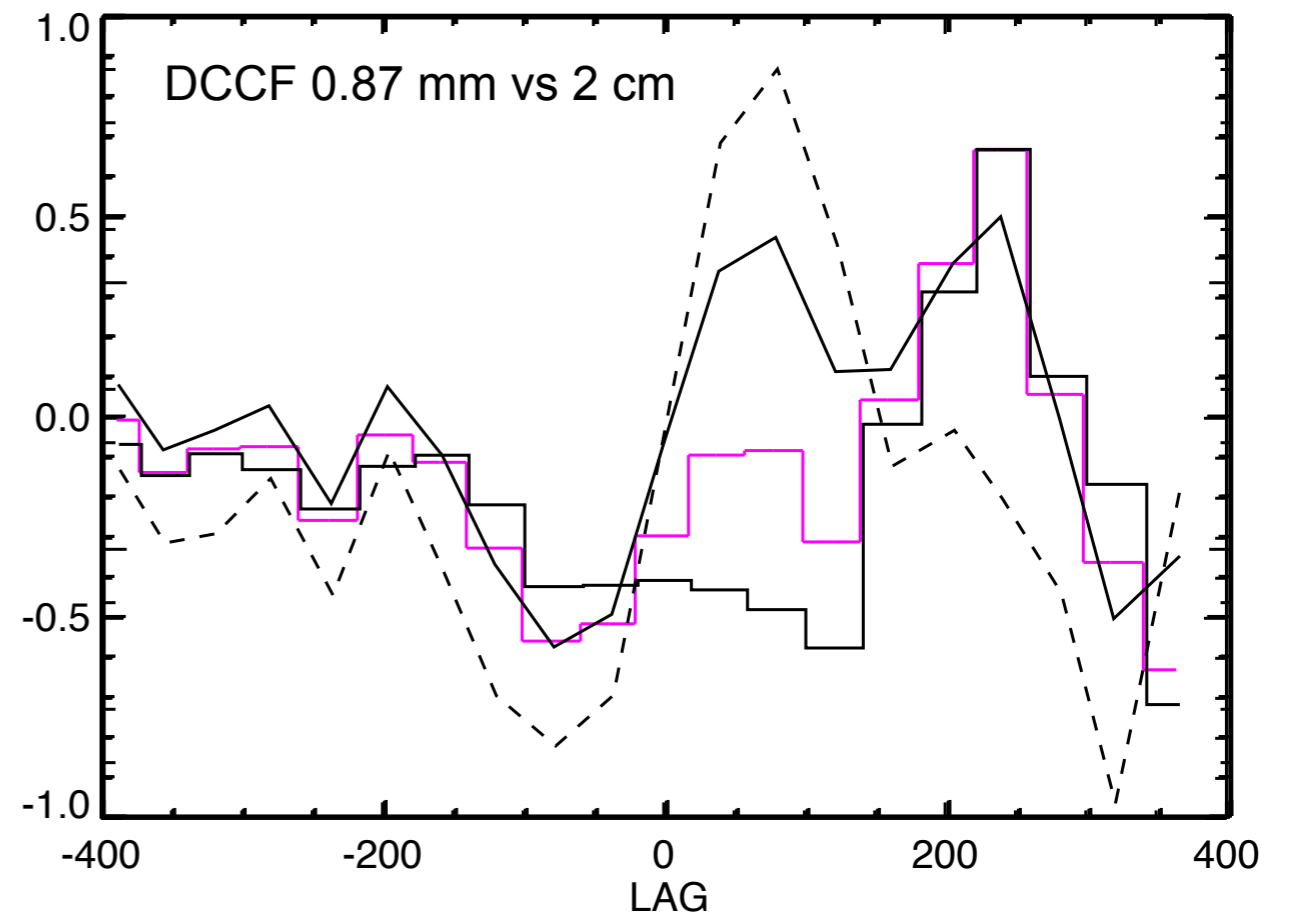
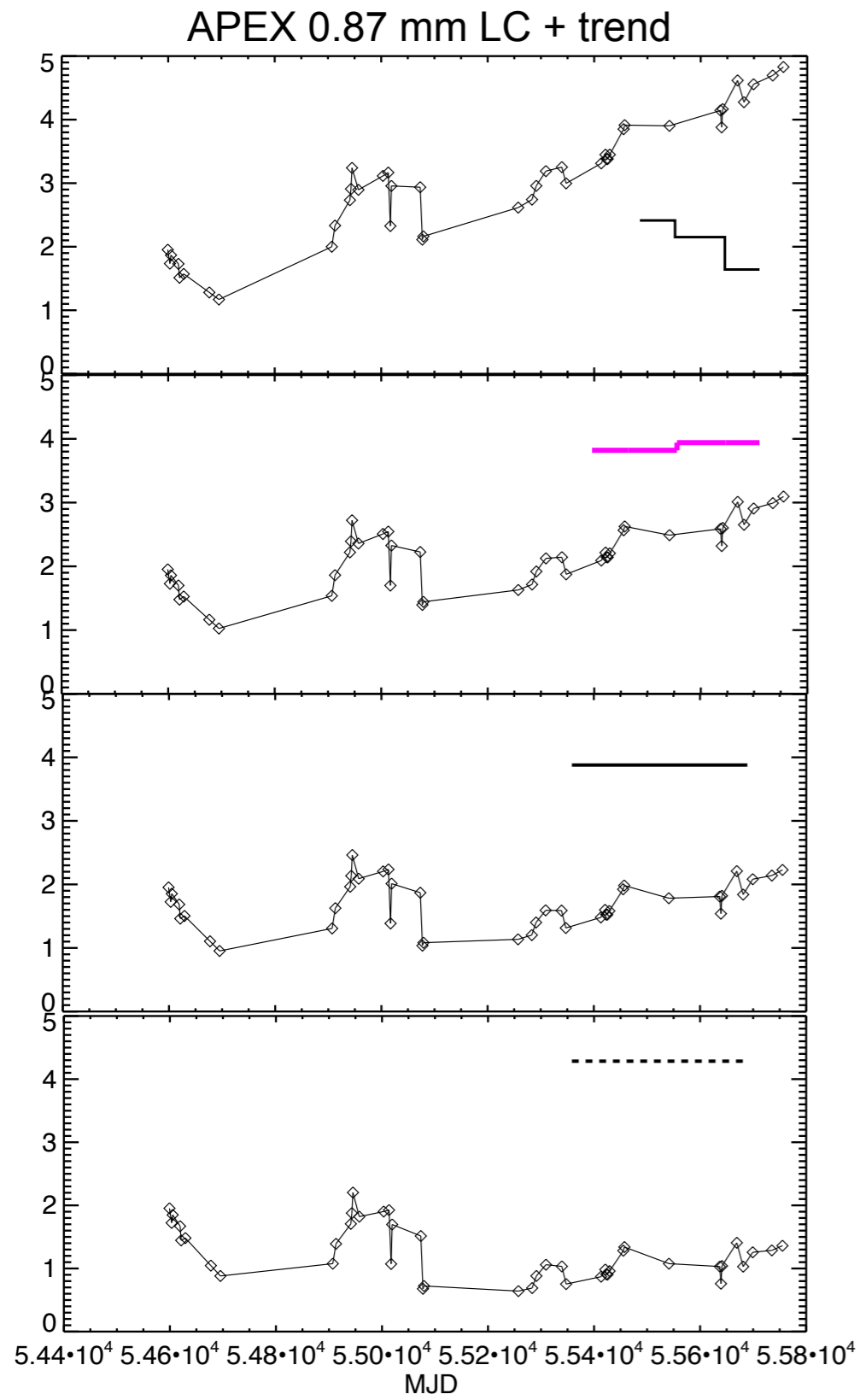
Will:

Reduce bias in Lag determination (property of the CCF, see e.g. Welsh, 1999)

May increase or decrease S/N in lag determination (Long time scales have few points and tend to be noisy but if detrending removes most of the signal we are left with noise)

Reduce the sensitivity on long time scales (Long and short time scales may have different correlation properties).

# THE EFFECT OF ADDING A TREND





The challenge for correlation analysis:

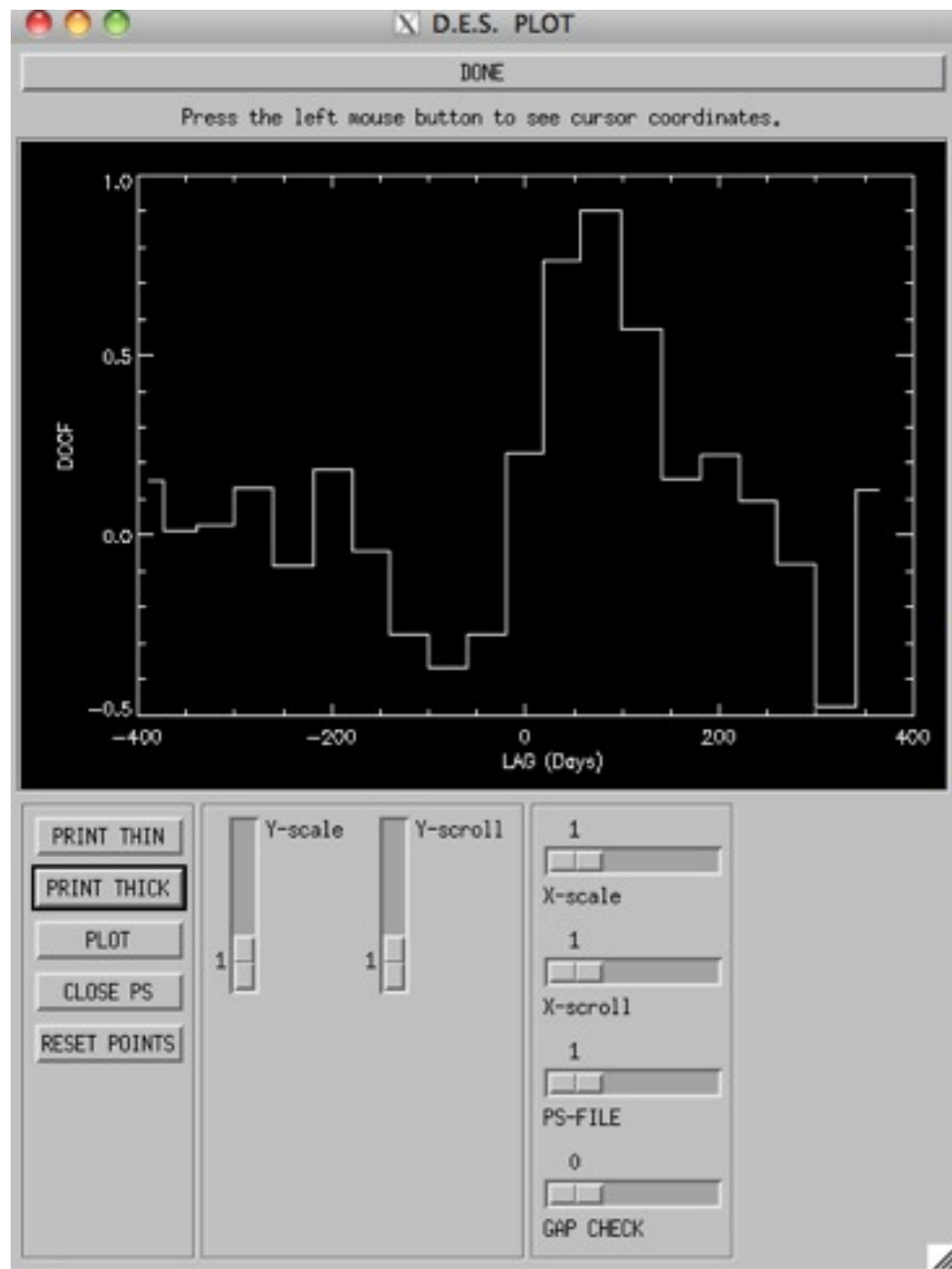
**Complexity**: More than one simultaneous type of correlation.

**Non-stationarity**: Variability and/or correlation properties changing with time. Depends on time scale.

**Patience** (long LCs) is needed to disentangle these effects.

# DES - Data Exploration System

<http://ttt.astro.su.se/groups/head/SL/des7.html>



OPTIONS (- # for help)

```
0. Active data array: 1 Points: 0
1. READ FILE 2. STATISTICS 3. DETREND 4. SELECT PART
5. BIN 6. SMOOTH 7. WRITE FILE 8. VIEW ARRAY
9. PARAMETERS 10. FFT
13. UNEVEN PS 14. ADBIN-PDS 15. CROSS SPEC 16. PDS
17. ACF 18. CCF 19. FIT 20. STATUS
21. TRANSF. 22. RESET 24. FOLD 25. EPHEMERIS
26. NOISE 27. ANALYSE PS 28. FLARES 29. AUTO PLOT
30. PLOT 31. COPY ARRAY 32. PHOTOMETRY 33. AUTOSIM.
34. SIMULATION 35. SIM-LOOP 36. PDS-FIT 37. DISTRIB
38. TIME SCALE 39. TIME DELAY
76. AUTOBACKUP 77. BACKUP 80. POLARIMETRY
90. INFO 99. EXIT
```

DISCRETE CORRELATION FUNCTION

0. Return to main menu
1. Routine: Binned UDCF
2. Max time Lag: 400.
3. Binning: Fixed time bins
4. Bin width: 40.
5. Lag estimate: None
6. Lag range for fit: -5. to 5.
7. Correction for white noise: NO
8. Error estimate: Error randomization and sampling bootstrap
9. Number of error runs: 600  
Apply MC errors to array(s): x1 and x2
11. Test mode: No
10. Compute DCCF