

National Aeronautics and Space Administration



Fermi

Gamma-ray Space Telescope

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**Users Group Meeting
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LAT Onboard GRB Search

J. McEnery

LAT Onboard GRB Search

- **Select events, onboard recon**
 - **Filter for gamma-like events**
 - currently all events passing gamma-filter, but would like to look for additional background rejection.
 - **Reconstruct onboard tracks**
 - **Combine 2-D projections to find 3-D tracks, select “best” track.**
- **Tier 1 - Pretrigger**
 - **Search through sliding windows of fixed number of events for clusters in space and time.**
 - **Pass into tier 2 if cluster prob exceeds a predefined threshold**
- **Tier 2 - Trigger (get here from Tier 1, or from GBM seed location)**
 - **Compile event list within Tier 1 or GBM seed location radius.**
 - **Declare a GRB if probability exceeds a predefined threshold**
- **Burst refinement**
 - **Localization obtained by iteratively calculated weighted mean location**
 - **Recalculate location at sequence of configurable **count thresholds**.**
 - **Alert notices sent out at **fixed time intervals**: 1, 2, 4, 8, 16, 32, 600 seconds**

LAT GRB Search - GBM Seeded Search

- **GBM sends trigger location to LAT at 2 5 10 20 30 60 90 and 150s**
- **Ra, Dec from GBM trigger is used as the seed location for search (LAT search commences when GBM message arrives)**
- **Current config**
 - **Onboard threshold is $TS > 0$, so always trigger immediately on detection of first LAT event within 10 deg of GBM location.**
 - **We apply a filter of $TS > 120$ on the ground before sending GCN notice.**
- **Two reasons to change this**
 - **Enabling a delayed search, by not triggering on the first GBM message, we allow the possibility of triggering on later ones.**
 - **Allowing the LAT-only search to run without hindrance**
 - **Long LAT searches will not trigger if the GBM seeded window has already generated a spurious trigger and put the LAT in GRB mode.**
- **Optimize and test updated config using existing LAT-detected bursts**
 - **Now complete, new configuration will be uploaded within the next two weeks**
 - **Localizations range from 0.1 to 0.5 deg typically.**

LAT GRB Search

Potential detections with new configuration:

GRB	2s	5s	10s	20s	30s	60s	90s	150s
• 080825	n	n	n	n	n	n	n	n
• 080916C	n	y						
• 081024B	y							
• 090227	n	n	n	n	n	n	n	n
• 090323	n	n	n	n	n	n	n	n
• 090328	n	n	n	n	n	n	n	n
• 090510*	y							
• 090626	n	n	n	n	n	n	n	n
• 090902	n	n	y	y				
• 090926	n	y						
• 091003	n	n	n	n	n	n	n	n
• 091031	n	n	n	n	n	n	n	n
• 100116*	n	n	n	n	n	n	n	n



Questions?

Test Statistics and Search Method

$$P_S = \sum_{i=1}^M |\log_{10}(p_{s_i})| = \sum_{i=1}^M \left| \log_{10} \left(\frac{1 - \cos(\theta_i)}{1 - \cos(\theta_m)} \right) \right|.$$

$$P_T = \sum_{i=1}^M |\log_{10}(p_{t_i})| = \sum_{i=1}^M \left| \log_{10}(1 - e^{-r_i \Delta T_i}) \right|.$$

- **Tier 1**
 - Consider n events from entire sky (n = 40 or 80)
 - For each event calculate P_S and P_T using all events within a 17 deg radius using the ra, dec of the first event as a seed position.
 - $P_S + P_T$ is roughly proportional to the number of events -> theta dependence
 - If $P_S + \alpha P_T > \text{Thres1}$ pass into Tier 2 ($\alpha=1$)
- **Tier 2**
 - Use the location from Tier 1 as a seed location (or a GBM position)
 - Calculate P_S and P_T for N_{prev} events ($N_{\text{prev}}=200$ for LAT and 500 for GBM seeds), add additional events to the P_S, P_T calculation until $P_S + \alpha P_T > \text{Thres2}$, or 1 second has elapsed since entering tier 2 (this means that we can't set Thres2 low to determine the null distribution)